

# **Autonomous Mobile Robots**

# HD-1500

# Autonomous Mobile Robots that self-navigate to transport payloads up to 1500 kg

- Natural feature navigation:
   Automatically plans efficient routes and prevents collisions;
   capable of full reverse navigation
- Fleet management:
   Scale deployment with AMR prioritization and multi-robot coordination for manufacturing environments
- Easy integration:
   Installs quickly, without facility modifications



# Ordering Information

Туре	HAPS	Charging Station	Pendant	Top Plate	Ordering Code
	No	No		37483-00000	
HD-1500	NO	Yes		37483-10004	
ПО-1900	Double	No			37483-00200
	Double	Yes			37483-10204

Note: 1. All AMRs in a fleet must have the same version of the FLOW Core software installed. Other considerations must be made when adding AMRs to a fleet. Contact your local OMRON representative for more information.

#### Items Included With the AMR

Item	Description
Labels	Lifting, warning, and product labels
USB Drive	Contains digital product documentation and software for operating the AMR
Printed Documentation	Printed manuals and guides for unpacking and operating the AMR
Lift Kit	Includes straps and hardware for lifting the AMR

<sup>2.</sup> The battery for the HD-1500 must be ordered separately (part number 68330-000). Before ordering lithium-ion batteries, please verify local shipping regulations to ensure compliance with applicable laws and restrictions.

# **Accessories and Optional Items**

Ito	em	<b>Details</b>	Ordering Code
Supplementary Laser Scanner Kit		Includes 2 supplementary laser scanners, mounting kit, cables, and hardware	68945-030
Supplementary Laser Scanner		One cable, 1 m length	22115-000F
Extension Cable, Co	ommunication	One cable, 2 m length	22117-000F
Supplementary Las	er Scanner	One cable, 1 m length	22800-000F
Extension Cable, Po	ower	One cable, 2 m length	22802-000F
Mobile I/O Box		Used with a Fleet Manager to summon an AMR to a goal or control connected devices with I/O	23419-802
Mobile I/O Box Pow	er Supply	Recommended for purchase with the Mobile I/O Box	23419-812
Top Plate Kit		Upper plate kit of the AMR Includes: access panel cover and cover seal, load plate, hardware and label	68950-000
Pendant		Handheld, external input device for manually driving an AMR Typically used for map creation	68940-000L
a a	Power Supply Box	Supplies power to the Docking Target or battery for charging purposes	73999-000
Charging Station	Docking Target	A fixed object connected to the Power Supply Box that the AMR docks to for autonomous charging	68910-030
Battery *		Removable and rechargeable power source for the AMR	68330-000
Wireless Antenna Extension Kit		Includes two dipole antennas, two 2 m coaxial cables, and two 0.6 m coaxial cable	68955-000
High Accuracy Positioning System (HAPS), Single Sensor		AMR Alignment using magnetic floor tape. Includes single HAPS sensor kit	68925-010
High Accuracy Positioning System (HAPS), Double Sensor		AMR Alignment using magnetic floor tape. Includes double HAPS sensor kit	68925-020
High Accuracy Positioning System (HAPS) Magnetic Tape		25 mm wide magnetic tape (South top side, 49 m roll)	14925-000

<sup>\*</sup>Before ordering lithium-ion batteries, please verify local shipping regulations to ensure compliance with applicable laws and restrictions.

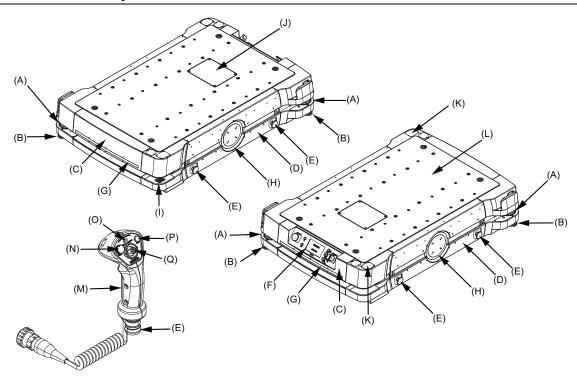
## **Software Licenses**

Product Name	Applicable For	Configuration	Ordering Code
Fleet Operations Workspace Core Fleet Manager License, 3 Year		Initial entitlement for a 3-year renewable FLOW Core license. Replace □□ with a value of 05 to 30, or 50 to indicate the number of AMRs licensed to connect. For 31 or more AMRs, use 50.	30271-1□□ *1
Fleet Operations Workspace Core Fleet Upgrade	Virtual Fleet	Entitlement for fleet connection limit increase by one additional AMR (used for existing installations)	30271-001
Fleet Operations Workspace Core Renewal	Manager	Entitlement for a 1-year renewal of the FLOW Core license. Replace \( \subseteq \subseteq  with a value of 05 to 30, or 50 to indicate the number of AMRs licensed to connect. For 31 or more AMRs, use 50.	30271-2□□
Fleet Operations Workspace		Entitlement for a 1-year renewable FLOW iQ license	30271-701
iQ License (FLOW iQ)		Entitlement for a 3-year renewable FLOW iQ license	30271-703
Cell Alignment Positioning System (CAPS) License	AMR	AMR Alignment using software-defined target Entitlement for a perpetual CAPS license	20271-805

<sup>\*1.</sup> After expiration of a FLOW Core Fleet Manager license, all Virtual Fleet Manager functionality will continue to operate without requiring subscription renewals. An active subscription will still be required to access subsequent software releases, including bug fixes, feature upgrades, and performance improvements.

**Note:** To upgrade to the latest version of the FLOW Core software, contact your local OMRON representative. Please note that an active subscription is required for access to software upgrades.

# **Features and Components**



Item	Description	Item	Description
Α	Safety Laser Scanner	J	User Access Panel
В	Low Laser	K	Wireless Antennas
С	Front / Rear Skin	L	Payload Mounting Surface (Top Plate shown)
D	Side Skin	М	Three-Position Enabling Switch
E	E-STOP Button*	N	Speed Control
F	Operator Panel	0	Power Indicator LED
G	Light Strip	Р	Goal Button
Н	Light Disc	Q	Directional Control Stick
	Charging Contacts	•	•

<sup>\*</sup>An additional E-STOP button is provided on the Operator Panel.

# HD-1500

# **Specifications**

	Item	Details
Weight (with B	attery)	506.5 kg
,	Ambient Temperature	5 to 40°C
	Storage Temperature	-20 to 60°C
	Ambient Humidity	5 to 95% (non-condensing)
	Operating Environment	Indoor usage only; no excessive dust, no corrosive gas or liquid
Environment	Altitude	2000 m max.
	Ingress Protection Class	IP20
	Dust / Smoke	< 1.5 mL / m² of dust with a particle size > 37 μm, avoid smoky areas
	Enclosure Rating	Type 1
	Cleanroom Rating	ISO 5 / Class 100
	Floor Requirements	No water, no oil, no dirt
	Minimum Floor Flatness	F <sub>F</sub> 25 (ACI 117 standard)
	Traversable Step *1	15 mm max.
Floor Conditions	Traversable Gap	20 mm max.
Conditions	Maximum Slope	5° / 8.75% incline
	Minimum Floor Compressive Strength	5 MPa
	Minimum Coefficient of Friction	0.6
	Routing	Autonomous routing by localizing with safety scanning laser, based on environment mapping
Navination	Environmental Map-Making Method	Scan by driving the AMR through the environment, and upload the scan data to MobilePlanner
Navigation	Low Lasers	Two Low Lasers are provided to detect obstacles below the scanning plane of the Safety Laser Scanners
	Supplementary Lasers (optional)	Two optional, Supplementary Lasers can be added for object detection in the vertical plane
Visual Indicato	rs	Light discs are located on the sides of the AMR. Light strips are located on the front and back of the AMR. Additional indicators can be added
Maximum Payload Capacity		1500 kg
	Run Time *2	12.5 h (no payload), 9 h (full payload)
	Maximum Translational Speed (forward and reverse)	1800 mm/s
	Maximum Rotational Speed *3	60 °/s
	Swing Radius	982 mm
	Turn Radius	0 mm
	Maximum Translational Acceleration	900 mm/s <sup>2</sup>
Mobility	Maximum Rotational acceleration/deceleration	150 °/s²
	Maximum Moment of Inertia	490 kg-m <sup>2</sup>
	Stop Position Repeatability (single AMR) *4	To a position: ±70 mm, ±2° To standard target: ±25 mm, ±2° With HAPS: ±8 mm, ±0.4° With CAPS: ±5 mm, ±0.4°
	Stop Position Repeatability (Fleet) *4	To a position: ±75 mm, ±2° To standard target: ±35 mm, ±2° With HAPS: ±10 mm, ±0.75° With CAPS: ±16 mm, ±0.5°
Drive wheels	Materials	Non-marking, static dissipative polyurethane on steel rim
Passive Casters	Materials	Non-marking polyurethane on cast iron rim
Auxiliary	Unregulated	48 to 57 VDC (52.8 nominal); 50 A fused
Power	Regulated	23.0 to 25.2 VDC; two channels fused at 1.85 A
	AMR	EN ISO 12100, EN ISO 13849-1, EN 60204-1, ISO 10218-1, EN 61000-6-2, EN 61000-6-4, EN ISO 3691-4 (except 4.12), CAN/UL 3100, CSA Z434
	Battery	ANSI/CAN/UL/ULC 2271, UN 38.3
	Charging Station	UL1012, CSA C22.2.107.2, EN 61204-7 used in conjunction with EN 62477-1
	Wireless	IEEE 802.11a/b/g
		·

Item		Details
	AMR	cTUVus
Marking	Battery	cURus
	Charging Station	cTUVus
	Wireless	Two integrated wireless antennas
	Ethernet Port	Two RJ-45 ports included for maintenance and access to the internally mounted NX102 unit
Signal Interfaces	Digital I/O	Eight PNP (sourcing) inputs Eight PNP (sourcing) outputs
	Analog I/O	Four -10 to +10 VDC analog inputs Four -10 to +10 VDC analog outputs
	Audio	Digital audio out
	Safety Scanning Lasers	Two Safety Scanning Lasers are included to provide a 360° detection area around the AMR. The scanning plane is positioned 181 mm above the floor.  Lasers are rated as Class 1, eye-safe, PLd Safety per ISO 13849-1.
	Safety Laser Scanner Zone Sets	A pair of safety-rated alternate safety zone inputs can toggle the Safety Laser Scanner zones between a default configuration or an alternate configuration.
Safety Features	E-STOP Buttons	Five E-STOP buttons are located on the AMR (sides and Operator Panel).  Additional E-STOP buttons can be added to the payload structure.
	Audible Indicators	Two speakers are included. Additional buzzers can be added.
	Emergency Stop Interface	Dual channel emergency stop inputs and outputs
	Safety Outputs	Dual channel safety outputs
	Protective Stop Interface	Dual channel protective stop inputs
	Display	7-inch diagonal LCD
Operator Panel	Controls	E-STOP button     ON/OFF buttons     Brake release button     Pendant port     Maintenance port     Main disconnect switch

<sup>\*1.</sup> A speed of 500 mm/s in the forward direction and 400 mm/s in the reverse direction is recommended for traversing steps. Routine driving over steps should be avoided. Lower speeds may not traverse the step. Faster or frequent driving over steps and gaps will shorten the lifespan of the drivetrain components. All steps should have smooth, rounded profiles.

\*2. Auxiliary power draw will impact these times.

<sup>\*3.</sup> The maximum rotational speed is reduced to 45 °/s when the AMR is traveling at speeds over 300 mm/s.
\*4. Stop position repeatability values were obtained using default AMR parameters and a map created by the HD-1500 AMR.

MobilePlanner Software Requirements			
	Operating System	Windows 10 (32/64-bit version)	
	СРИ	1.5 GHz dual-core CPU recommended	
MobilePlanner,	Main Memory	1.5 GB min. (4 GB recommended)	
PC	Hard Disk	At least 400 MB of available space	
	Video Memory Display	256 MB min.	
		XGA 1280 x 720, 16 million colors minimum	
MobilePlanner, Tablet Edition	Operating System	Android OS, Version 9 or newer, minimum 2 GB of RAM	
		iOS, Version 10 or newer	

English, German, Japanese, French, Italian, Korean, Spanish,

Simplified Chinese and Traditional Chinese.

# **Virtual Fleet Manager Software Minimum Hardware Requirements**

Fleet Size / AMR Count	Small / ≤ 5	Medium ≤ 15	Large ≤ 30	X-Large > 30 <b>*</b>
Virtual CPU	2 cores		4 cores	
Clockspeed	4GHz	8 GHz	12 GHz	16 GHz
Virtual RAM	8 GB	16 GB	24 GB	32 GB
Virtual Disk	512 GB 1 TB			1 TB
FLOW Software Version	Minimum FLOW Core 4.0			

<sup>\*</sup> Contact your local OMRON representative for fleets larger than 100.

Note: The PC/IPC/Server is supplied by the user.

**Charging Station** 

**Supported Languages** 

Maximum Current	Input current: 25 A Output current: 120 A (nominal) *
Input Voltage	3-phase 200 to 240 VAC, 50/60 Hz (Delta/Wye) 380 to 415 VAC, 50/60 Hz (Wye only)
Output Voltage	40 to 57 VDC
Power Consumption	7.75 kW
Maximum Power Output	6.84 kW
Humidity	5 to 95%, non-condensing
Ambient Operating Temperature	5 to 40°C
Storage Temperature	-20 to 60°C
Ingress Protection	IP20 (IP10 for charging pads)
Pollution Degree	2
Equipment Class	1
Weight	Power Supply Box: 108 kg Docking Target: 27.5 kg
Docking Target Mounting	To floor and/or wall

<sup>\*</sup>Fused at 150 A

High Accuracy Positioning System			
Ingress Prote	ction	IP64	
Environment		-40 to 85°C	
Magnetic	Width	25 mm	
Tape	Orientation	South up	
	Width	25 mm	
Markers (Magnetic	Length	300 mm min. for 500 mm/s drive speed	
Tape)	Orientation	North up	
	Separation from Tape	20 to 30 mm	
Protective Covering Tape (recommended)		Mighty Line Safety Floor Tape, Solid (102 mm width)	

#### **Pendant**

Ambient Operating Temperature	0 to 40°C
Storage Temperature	-20 to 65°C
Humidity	5 to 95%, non-condensing
Altitude	2000 m
Ingress Protection Class	IP30

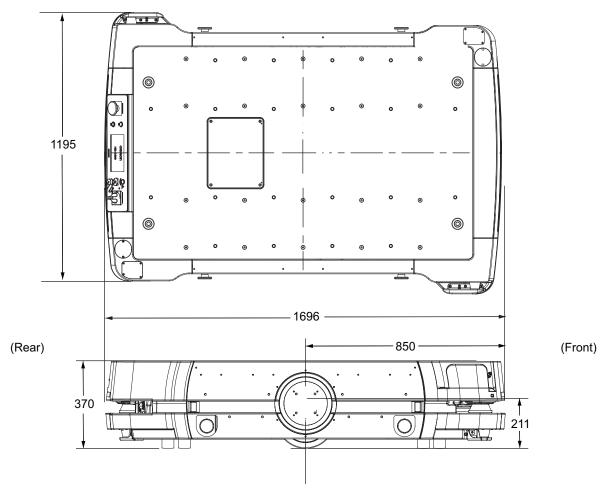
#### **Battery**

Dattory	
Туре	Lithium-Ion (LiFePO4)
Voltage	48 to 57 VDC (52.8 nominal)
Capacity	68 Ah nominal
Recharge Time	24 min. (20% to 80% charge)
Charge Cycles	Approximately 8000 cycles *
Charging Method	Automatic or manual
Ambient Operating Temperature	5 to 40°C
Storage Temperature	-20 to 60°C (less than 2 weeks) -20 to 35°C (more than 2 weeks)
Humidity	5 to 95%, non-condensing
Altitude	4500 m, operating 15240 m, transporting
Ingress Protection	IP20
Weight	69.5 kg

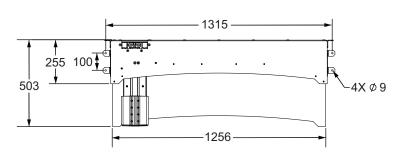
<sup>\*</sup>Approximately 80% of nominal battery capacity will be available after using the battery at 100% depth of discharge, at a temperatures of 23°C.

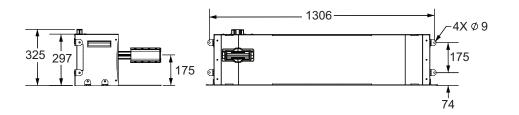
**Dimensions** (Unit: mm)

## HD-1500 AMR

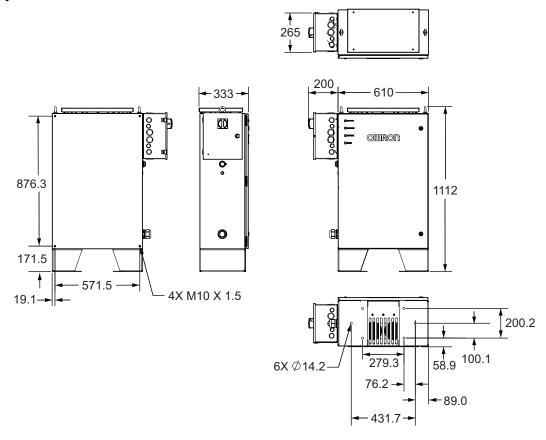


# **Docking Target**





#### **Power Supply Box**



# **Related Manuals**

Manual No.	Title	
I614	Mobile Robot Software Suite User's Guide	
I617	Advanced Robotics Command Language Reference Manual	
I618	Advanced Robotics Command Language Enterprise Manager Integration Manual	
1635	Fleet Operations Workspace Core User's Manual	
1636	Fleet Operations Workspace Core Migration Guide	
1637	Fleet Operation Workspace Core Integration Toolkit User Manual	
1665	Fleet Operations Workspace iQ User's Manual	
1649	Fleet Simulator User's Manual	
1695	Virtual Fleet Manager Installation Guide	
1645	HD-1500 Platform User's Manual	
1647	AMR (Autonomous Mobile Robot) HD-1500 Platform Safety and Unpacking Guide	
1677	Mobile I/O Box User's Manual	

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Note: Do not use this document to operate the Unit. This document describes AMR functionality supported with FLOW v3.3.6 and hardware revision V or higher. Contact your local OMRON representative for older version functionality details.

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